

## Numerical Analysis — FMN011 — 100528

The exam lasts 4 hours and has 13 questions. A minimum of 35 points out of the total 70 are required to get a passing grade. These points will be added to those you obtained in your two home assignments, and the final grade is based on your total score.

**Justify all your answers and write down all important steps.** Unsupported answers will be disregarded.

During the exam you are allowed a pocket calculator, but no textbook, lecture notes or any other electronic or written material.

- (6p)** Suppose a numerical method is used to solve the fixed point problem  $x = g(x)$ , where  $g : \mathbb{R} \rightarrow \mathbb{R}$  and the computed value of  $x$  is  $\hat{x}$ . Suppose the exact value of the solution is  $x^*$ .
  - Write the formula for the absolute error of the approximation.
  - Write the formula for the relative error of the approximation.
  - Write the formula for the residual or backward error.
- (4p)** If a function  $f : \mathbb{R} \rightarrow \mathbb{R}$  is approximated by its degree 3 Taylor polynomial centered at 0, write the formula for the truncation error.
- (5p)** Fill in the blanks (marked -->) to complete this implementation of the bisection method. What mathematical problem does it solve?

```
function [c,max_possible_err,res] = bisection(f,a,b,tol)
% f(a), f(b) must have opposite signs
% c is the approximate solution
--> while (b-a)/2 >
-->     c =
        if f(c)*f(a) > 0
-->         a =
        elseif f(c)*f(b) > 0
-->         b =
        else break
        end
    end
--> max_possible_err =
    res = f(c);
```

- (4p)** Illustrate three iteration steps of the Newton-Raphson method

$$p_{k+1} = p_k - \frac{f(p_k)}{f'(p_k)}$$

applied to the function displayed on the last page (page 5) of this exam, with starting point at  $x_0 = 3$ . Clearly mark each of the iterates  $x_j$ . You may detach this page, work out the result and hand it in with your answers.

5. The following Matlab code does Gauss elimination on a system  $Ax = b$ .

```

for j=1:n-1
    for i=j+1:n
        m=a(i,j)/a(j,j);
        b(i)=b(i)-m*b(j);
        for k=j+1:n
            a(i,k)=a(i,k)-m*a(j,k);
        end
    end
end
end

```

(a) **(3p)** Modify the code to optimize it for tridiagonal matrices, i.e. with structure

$$\begin{pmatrix} X & X & & & \\ X & X & X & & \\ & \ddots & \ddots & \ddots & \\ & & X & X & X \\ & & & X & X \end{pmatrix}$$

(b) **(3p)** Count the number of arithmetic operations (additions, subtractions, multiplications, divisions and square roots) needed to solve a system of  $n$  equations with a tridiagonal matrix. You may use the formulas

$$\sum_{k=1}^N k = \frac{N(N+1)}{2}, \quad \sum_{k=1}^N k^2 = \frac{N(N+1)(2N+1)}{6}$$

6. **(5p)** Specify an elementary matrix that zeros out the last 3 components of vector  $[1 \ 2 \ 3 \ 4 \ 5]^T$ .

7. (a) **(2p)** Why is interpolation by a polynomial of high degree often unsatisfactory?
- (b) **(2p)** To guarantee convergence of a polynomial interpolation to sufficiently smooth functions as the number of points increases on an interval, how should the interpolation points be placed?
- (c) **(2p)** For uniformly spaced points, is the error in a Lagrange interpolation greater around the middle of the interval or near the endpoints?
- (d) **(2p)** How many roots does the Chebyshev polynomial of order  $n$  have in  $(-\infty, \infty)$ ? In  $[-1, 1]$ ?
- (e) **(2p)** A linear change of interval between  $[-1, 1]$  and  $[a, b]$  can be accomplished by the formula

$$x = \frac{b-a}{2}t + \frac{a+b}{2}.$$

If the zeros of the  $n$ -th degree Chebyshev polynomial are

$$x_k = \cos \frac{(2k-1)\pi}{2n},$$

which points should you use as  $x$ -data points to do a Chebyshev interpolation in the interval  $[0, 4]$ ?

8. **(5p)** Describe the relation between the discrete Fourier transform  $y = F_n x$  and the polynomial

$$P_n(t) = \frac{1}{\sqrt{n}} \sum_{k=0}^{n-1} \left( a_k \cos \frac{2\pi k(t-c)}{d-c} - b_k \sin \frac{2\pi k(t-c)}{d-c} \right), \quad t \in [c, d].$$

9. **(5p)** The first 9 components of the discrete Fourier transform of a vector  $x \in \mathbb{R}^{16}$  are  $136, -8 + 40.219i, -8 + 19.314i, -8 + 11.973i, -8 + 8i, -8 + 5.3454i, -8 + 3.3137i, -8 + 1.5913i, -8$ . What are the missing components?
10. (a) **(2p)** The Shannon information formula is

$$I = - \sum_{i=1}^k p_i \log_2 p_i$$

Calculate the average least number of bits needed to code the matrix

$$A = \begin{pmatrix} 4 & 7 & 7 \\ 9 & 0 & 8 \\ 8 & 8 & 7 \end{pmatrix}$$

- (b) **(2p)** Construct the Huffman code for  $A$ .
- (c) **(2p)** What is the average for this coding? What is the average if the standard binary system is used for the matrix entries?
11. **(5p)** True or false (support your answer with a short explanation or counterexample):
- The DFT implies a periodic extension of the function defined over a finite interval, and the DCT implies an even extension of the function.
  - The discrete cosine transform is a linear transformation that is not necessarily invertible.
  - The order of complexity of the DCT algorithm is the same as that of the DFT algorithm.
  - Quantization and Huffman coding are examples of lossy compression.
  - In the SVD of matrix  $A$ , the columns of  $U$  are orthonormal eigenvectors of  $AA^T$ .

12. **(4p)** The  $QR$  factorization of matrix  $A$  is

$$\begin{pmatrix} 0.24759 & 0.51408 & 0.67406 & -0.4691 \\ 0.55709 & -0.76621 & 0.29789 & -0.11762 \\ 0.49519 & 0.29563 & 0.15133 & 0.8028 \\ 0.61898 & 0.24745 & -0.65879 & -0.34875 \end{pmatrix} \begin{pmatrix} 16.155 & 11.266 & 12.132 & 6.3136 \\ 0 & 8.1907 & 0.52812 & 4.1356 \\ 0 & 0 & 5.5257 & 6.3735 \\ 0 & 0 & 0 & 2.1007 \end{pmatrix}$$

Can you give the eigenvectors of  $A$  from this information?

13. (5p) The  $QR$  algorithm for matrix  $A$  is

$$\begin{aligned}A_0 &\equiv A = Q_1 R_1 \\A_1 &\equiv R_1 Q_1 = Q_2 R_2 \\A_2 &\equiv R_2 Q_2 = Q_3 R_3 \\&\vdots \\A_k &\equiv R_k Q_k\end{aligned}$$

If  $A$  is a symmetric matrix with eigenvalues  $|\lambda_1| > |\lambda_2| > \cdots > |\lambda_n|$ , where do we find the eigenvalues of  $A$ ? How do we find the eigenvectors of  $A$ ?

Illustration of the first 3 iteration steps of the Newton-Raphson method applied to the function plotted below, starting at  $x_0 = 3$

